

VAR modelling for monetary policy analysis: Appendix

Innovation accounting: a bivariate example

Consider a stationary bivariate VAR system in $VMA(\infty)$ representation (omitting constant terms for simplicity):

$$\mathbf{y}_t = \Phi_0 \mathbf{v}_t + \Phi_1 \mathbf{v}_{t-1} + \Phi_2 \mathbf{v}_{t-2} + \dots + \Phi_s \mathbf{v}_{t-s} + \dots$$

written in full form as:

$$\begin{pmatrix} y_{1t} \\ y_{2t} \end{pmatrix} = \begin{pmatrix} \phi_{0,11} & \phi_{0,12} \\ \phi_{0,21} & \phi_{0,22} \end{pmatrix} \begin{pmatrix} v_{1,t} \\ v_{2,t} \end{pmatrix} + \begin{pmatrix} \phi_{1,11} & \phi_{1,12} \\ \phi_{1,21} & \phi_{1,22} \end{pmatrix} \begin{pmatrix} v_{1,t-1} \\ v_{2,t-1} \end{pmatrix} + \\ + \begin{pmatrix} \phi_{2,11} & \phi_{2,12} \\ \phi_{2,21} & \phi_{2,22} \end{pmatrix} \begin{pmatrix} v_{1,t-2} \\ v_{2,t-2} \end{pmatrix} + \dots + \begin{pmatrix} \phi_{s,11} & \phi_{s,12} \\ \phi_{s,21} & \phi_{s,22} \end{pmatrix} \begin{pmatrix} v_{1,t-s} \\ v_{2,t-s} \end{pmatrix} + \dots$$

Impulse response functions

The elements of the matrices Φ_i trace out the effects over time (*impulse response functions*) of each structural disturbance in \mathbf{v} keeping all the other disturbances at zero, under the set of identifying assumptions used ($\Phi_0 = \mathbf{A}^{-1}$). Each matrix Φ_s captures the effect of the structural shocks at time t on the endogenous variables at time $t + s$; the typical element

$$\phi_{s,ij} = \frac{\partial y_{i,t+s}}{\partial v_{j,t}}$$

captures the response of the i th element of \mathbf{y}_{t+s} to an “impulse” due to the j th element of \mathbf{v}_t . Noting that $\frac{\partial y_{i,t+s}}{\partial v_{j,t}} = \frac{\partial y_{i,t}}{\partial v_{j,t-s}}$, from the VMA representation above we get:

- *IRF* of y_1 to v_1 : $\phi_{0,11}, \phi_{1,11}, \phi_{2,11}, \dots$ (elements in position 1, 1 in $\Phi_0, \Phi_1, \Phi_2, \dots$)
- *IRF* of y_1 to v_2 : $\phi_{0,12}, \phi_{1,12}, \phi_{2,12}, \dots$ (elements in position 1, 2 in $\Phi_0, \Phi_1, \Phi_2, \dots$)
- *IRF* of y_2 to v_1 : $\phi_{0,21}, \phi_{1,21}, \phi_{2,21}, \dots$ (elements in position 2, 1 in $\Phi_0, \Phi_1, \Phi_2, \dots$)
- *IRF* of y_2 to v_2 : $\phi_{0,22}, \phi_{1,22}, \phi_{2,22}, \dots$ (elements in position 2, 2 in $\Phi_0, \Phi_1, \Phi_2, \dots$)

Forecast error variance decomposition

From the $VMA(\infty)$ representation of the VAR it is possible to obtain the forecast of future \mathbf{y} 's over an h -period horizon on the basis of information in current (time t) and past values of the variables in the system $\mathbf{y}_t, \mathbf{y}_{t-1}, \dots$. The associated forecast error is:

$$\mathbf{y}_{t+h} - E(\mathbf{y}_{t+h} | \mathbf{y}_t, \mathbf{y}_{t-1}, \dots) = \Phi_0 \mathbf{v}_{t+h} + \Phi_1 \mathbf{v}_{t+h-1} + \dots + \Phi_{h-1} \mathbf{v}_{t+1}$$

written in full form as

$$\begin{pmatrix} y_{1,t+h} - E(y_{1,t+h} | \mathbf{y}_t, \mathbf{y}_{t-1}, \dots) \\ y_{2,t+h} - E(y_{2,t+h} | \mathbf{y}_t, \mathbf{y}_{t-1}, \dots) \end{pmatrix} = \begin{pmatrix} \phi_{0,11} & \phi_{0,12} \\ \phi_{0,21} & \phi_{0,22} \end{pmatrix} \begin{pmatrix} v_{1,t+h} \\ v_{2,t+h} \end{pmatrix} + \\ + \begin{pmatrix} \phi_{1,11} & \phi_{1,12} \\ \phi_{1,21} & \phi_{1,22} \end{pmatrix} \begin{pmatrix} v_{1,t+h-1} \\ v_{2,t+h-1} \end{pmatrix} + \dots + \begin{pmatrix} \phi_{h-1,11} & \phi_{h-1,12} \\ \phi_{h-1,21} & \phi_{h-1,22} \end{pmatrix} \begin{pmatrix} v_{1,t+1} \\ v_{2,t+1} \end{pmatrix}$$

The *forecast error variance* is given by the following symmetric matrix

$$\text{var}(\mathbf{y}_{t+h} - E(\mathbf{y}_{t+h} | \mathbf{y}_t, \mathbf{y}_{t-1}, \dots)) = \mathbf{\Phi}_0 \mathbf{D} \mathbf{\Phi}'_0 + \mathbf{\Phi}_1 \mathbf{D} \mathbf{\Phi}'_1 + \dots + \mathbf{\Phi}_{h-1} \mathbf{D} \mathbf{\Phi}'_{h-1}$$

The elements on the main diagonal capture the forecast error variances of each variable in \mathbf{y} . Writing the matrix in full form we get:

$$\begin{aligned} & E \left[\begin{pmatrix} y_{1,t+h} - E(y_{1,t+h} | \mathbf{y}_t, \mathbf{y}_{t-1}, \dots) \\ y_{2,t+h} - E(y_{2,t+h} | \mathbf{y}_t, \mathbf{y}_{t-1}, \dots) \end{pmatrix} \begin{pmatrix} y_{1,t+h} - E(y_{1,t+h} | \mathbf{y}_t, \mathbf{y}_{t-1}, \dots) \\ y_{2,t+h} - E(y_{2,t+h} | \mathbf{y}_t, \mathbf{y}_{t-1}, \dots) \end{pmatrix}' \right] \equiv \\ & \equiv \begin{pmatrix} \text{var}(y_{1,t+h} - E(y_{1,t+h} | \mathbf{y}_t, \mathbf{y}_{t-1}, \dots)) & \text{cov}(.,.) \\ \text{cov}(.,.) & \text{var}(y_{2,t+h} - E(y_{2,t+h} | \mathbf{y}_t, \mathbf{y}_{t-1}, \dots)) \end{pmatrix} = \\ & = \underbrace{\begin{pmatrix} \phi_{0,11} & \phi_{0,12} \\ \phi_{0,21} & \phi_{0,22} \end{pmatrix}}_{\mathbf{\Phi}_0} \underbrace{\begin{pmatrix} \sigma_{v_1}^2 & 0 \\ 0 & \sigma_{v_2}^2 \end{pmatrix}}_{\mathbf{D}} \underbrace{\begin{pmatrix} \phi_{0,11} & \phi_{0,21} \\ \phi_{0,12} & \phi_{0,22} \end{pmatrix}}_{\mathbf{\Phi}'_0} + \\ & \quad + \underbrace{\begin{pmatrix} \phi_{1,11} & \phi_{1,12} \\ \phi_{1,21} & \phi_{1,22} \end{pmatrix}}_{\mathbf{\Phi}_1} \underbrace{\begin{pmatrix} \sigma_{v_1}^2 & 0 \\ 0 & \sigma_{v_2}^2 \end{pmatrix}}_{\mathbf{D}} \underbrace{\begin{pmatrix} \phi_{1,11} & \phi_{1,21} \\ \phi_{1,12} & \phi_{1,22} \end{pmatrix}}_{\mathbf{\Phi}'_1} + \dots \\ & \quad \dots + \underbrace{\begin{pmatrix} \phi_{h-1,11} & \phi_{h-1,12} \\ \phi_{h-1,21} & \phi_{h-1,22} \end{pmatrix}}_{\mathbf{\Phi}_{h-1}} \underbrace{\begin{pmatrix} \sigma_{v_1}^2 & 0 \\ 0 & \sigma_{v_2}^2 \end{pmatrix}}_{\mathbf{D}} \underbrace{\begin{pmatrix} \phi_{h-1,11} & \phi_{h-1,21} \\ \phi_{h-1,12} & \phi_{h-1,22} \end{pmatrix}}_{\mathbf{\Phi}'_{h-1}} = \\ & \text{(omitting off-diagonal covariance terms for ease of exposition)} \\ & = \underbrace{\begin{pmatrix} \sigma_{v_1}^2 \phi_{0,11}^2 + \sigma_{v_2}^2 \phi_{0,12}^2 & \dots \\ \dots & \sigma_{v_1}^2 \phi_{0,21}^2 + \sigma_{v_2}^2 \phi_{0,22}^2 \end{pmatrix}}_{\mathbf{\Phi}_0 \mathbf{D} \mathbf{\Phi}'_0} + \\ & \quad + \underbrace{\begin{pmatrix} \sigma_{v_1}^2 \phi_{1,11}^2 + \sigma_{v_2}^2 \phi_{1,12}^2 & \dots \\ \dots & \sigma_{v_1}^2 \phi_{1,21}^2 + \sigma_{v_2}^2 \phi_{1,22}^2 \end{pmatrix}}_{\mathbf{\Phi}_1 \mathbf{D} \mathbf{\Phi}'_1} + \dots \\ & \quad \dots + \underbrace{\begin{pmatrix} \sigma_{v_1}^2 \phi_{h-1,11}^2 + \sigma_{v_2}^2 \phi_{h-1,12}^2 & \dots \\ \dots & \sigma_{v_1}^2 \phi_{h-1,21}^2 + \sigma_{v_2}^2 \phi_{h-1,22}^2 \end{pmatrix}}_{\mathbf{\Phi}_{h-1} \mathbf{D} \mathbf{\Phi}'_{h-1}} = \\ & = \begin{pmatrix} \sigma_{v_1}^2 \sum_{s=0}^{h-1} \phi_{s,11}^2 + \sigma_{v_2}^2 \sum_{s=0}^{h-1} \phi_{s,12}^2 & \dots \\ \dots & \sigma_{v_1}^2 \sum_{s=0}^{h-1} \phi_{s,21}^2 + \sigma_{v_2}^2 \sum_{s=0}^{h-1} \phi_{s,22}^2 \end{pmatrix} \end{aligned}$$

At any horizon h , the forecast error variance for each variable i (with $i = 1, 2$) is the sum of two components: (i) $\sigma_{v_1}^2 \sum_{s=0}^{h-1} \phi_{s,i1}^2$, that captures the variance due to the first structural disturbance v_1 , and (ii) $\sigma_{v_2}^2 \sum_{s=0}^{h-1} \phi_{s,i2}^2$, capturing the variance due to v_2 . The *FEVD* exercise consists in computing the fractions of the total variance attributable to each of the two structural shocks. Letting $FEVD_{h,ij}$ denote the portion of the forecast error variance of variable i attributable to shock j at forecasting horizon h , we have:

- for a one-period forecasting horizon, $h = 1$:

$$FEVD_{1,11} = \frac{\sigma_{v_1}^2 \phi_{0,11}^2}{\sigma_{v_1}^2 \phi_{0,11}^2 + \sigma_{v_2}^2 \phi_{0,12}^2}, FEVD_{1,12} = \frac{\sigma_{v_2}^2 \phi_{0,12}^2}{\sigma_{v_1}^2 \phi_{0,11}^2 + \sigma_{v_2}^2 \phi_{0,12}^2} \quad \text{for } y_1$$

$$FEVD_{1,21} = \frac{\sigma_{v_1}^2 \phi_{0,21}^2}{\sigma_{v_1}^2 \phi_{0,21}^2 + \sigma_{v_2}^2 \phi_{0,22}^2}, FEVD_{1,22} = \frac{\sigma_{v_2}^2 \phi_{0,22}^2}{\sigma_{v_1}^2 \phi_{0,21}^2 + \sigma_{v_2}^2 \phi_{0,22}^2} \quad \text{for } y_2$$

- for a two-period forecasting horizon, $h = 2$:

$$FEVD_{2,11} = \frac{\sigma_{v_1}^2 \sum_{s=0}^1 \phi_{s,11}^2}{\sigma_{v_1}^2 \sum_{s=0}^1 \phi_{s,11}^2 + \sigma_{v_2}^2 \sum_{s=0}^1 \phi_{s,12}^2}, FEVD_{2,12} = \frac{\sigma_{v_2}^2 \sum_{s=0}^1 \phi_{s,12}^2}{\sigma_{v_1}^2 \sum_{s=0}^1 \phi_{s,11}^2 + \sigma_{v_2}^2 \sum_{s=0}^1 \phi_{s,12}^2} \quad \text{for } y_1$$

$$FEVD_{2,21} = \frac{\sigma_{v_1}^2 \sum_{s=0}^1 \phi_{s,21}^2}{\sigma_{v_1}^2 \sum_{s=0}^1 \phi_{s,21}^2 + \sigma_{v_2}^2 \sum_{s=0}^1 \phi_{s,22}^2}, FEVD_{2,22} = \frac{\sigma_{v_2}^2 \sum_{s=0}^1 \phi_{s,22}^2}{\sigma_{v_1}^2 \sum_{s=0}^1 \phi_{s,21}^2 + \sigma_{v_2}^2 \sum_{s=0}^1 \phi_{s,22}^2} \quad \text{for } y_2$$

and so on for more extended forecasting horizons. In general, for horizon h , variable i and shock j , we have:

$$FEVD_{h,ij} = \frac{\sigma_{v_j}^2 \sum_{s=0}^{h-1} \phi_{s,ij}^2}{\sigma_{v_1}^2 \sum_{s=0}^{h-1} \phi_{s,i1}^2 + \sigma_{v_2}^2 \sum_{s=0}^{h-1} \phi_{s,i2}^2}$$